

② Solution and vibratory property

Model in general form -

$$a_2 \ddot{y} + a_1 \dot{y} + a_0 y = 0 \quad (1)$$

$$\boxed{a_i's > 0}$$

ICs

$$y(0) = y_0$$

$$\dot{y}(0) = \dot{y}_0$$

$$y(t) = ?$$

Rewrite Eq. (1) in another form by dividing a_2 through =

$$\ddot{y} + \frac{a_1}{a_2} \dot{y} + \frac{a_0}{a_2} y = 0 \quad (2)$$

Recall

$$\omega_n^2 = \frac{a_0}{a_2}$$

(3)

Rewrite a_1/a_2 as

$$\frac{a_1}{a_2} = 2\omega_n \left(\frac{1}{2\omega_n} \frac{a_1}{a_2} \right)$$

define

$$\left[\frac{1}{2\omega_n} \frac{a_1}{a_2} \equiv \zeta \right] = \text{damping ratio} \quad (4)$$

Eq. (2) $\Rightarrow$

$$\left[\ddot{y} + 2\omega_n \zeta \dot{y} + \omega_n^2 y = 0 \right] \quad (5)$$

Two-parameter model w/ ω_n and ζ .

We work with Eq. (5)

$$y(t) = ?$$

Propose a solution by physical consideration:

$$y(t) = A \sin(\omega_n t + \phi) ?$$

No, because $y(t)$ must decrease to zero in time.

How about

$$y(t) = A e^{-at} \sin(\omega_d t + \phi) ? \quad a > 0$$

May not work because if ^{damping} is large, there might not be any free vibration.

How about $y(t) = A e^{st}$? (6)

Where s may be a complex number, $s = -a + ib$

If $s =$ negative real, $y(t)$ decays in time

$s =$ complex w/ negative real part

$$e^{st} = e^{(-a+ib)t} = e^{-at} e^{ibt} = e^{-at} (\cos bt + i \sin bt)$$

$\Rightarrow$ decayed vibration

Feels OK but unclear of "i". Try it any way.

$$\begin{aligned} i &= \sqrt{-1} \\ j &= \sqrt{-1} \\ &\uparrow \text{book} \end{aligned}$$

Verify

a): $y(t)$ ^{must} satisfy Eq. ⑤

$$\therefore \dot{y}(t) = \frac{d}{dt}(A e^{st}) = A s e^{st} = s y$$

$$\ddot{y} = \frac{d}{dt}(\dot{y}) = \frac{d}{dt}(A s e^{st}) = A s^2 e^{st} = s^2 y$$

plug into Eq. ⑤ $\Rightarrow$

$$s^2 y + 2\omega_n \zeta s y + \omega_n^2 y \stackrel{?}{=} 0$$

$$\text{or } \left[(s^2 + 2\omega_n \zeta s + \omega_n^2) y \stackrel{?}{=} 0 \right] \quad \text{⑦}$$

$\downarrow$
 $\neq 0$

So, s must satisfy Eq. ⑦ for Eq. ⑥ to qualify as a solution

Eq. ⑦ is called the characteristic eq. of the system

$$\text{Solving Eq. ⑦ for } s = \quad s_{1,2} = \frac{-2\omega_n \zeta \pm \sqrt{(2\omega_n \zeta)^2 - 4\omega_n^2}}{2}$$

$$\text{or } \left[s_{1,2} = \left(-\zeta \pm \sqrt{\zeta^2 - 1} \right) \omega_n \right] \quad \text{⑧}$$

$\uparrow$
 s_2

Three possible expressions for $y(t)$ depending on value of ξ .

case ① $\left| \xi > 1.0 \right| \Rightarrow$ ^{Eq ⑧} s_1, s_2 real and $s_1 \neq s_2$

Then Eq. ⑥ $\Rightarrow$

$$y_1(t) = A_1 e^{s_1 t}$$

or $y_2(t) = A_2 e^{s_2 t}$

either satisfies Eq ⑤

^{God says}
But $y(t)$ must be unique.

How about $y(t) = y_1(t) + y_2(t)$?

Verify to satisfy Eq. ⑤

$$\Rightarrow (\ddot{y}_1 + \ddot{y}_2) + 2\xi\omega_n(\dot{y}_1 + \dot{y}_2) + \omega_n^2(y_1 + y_2) \stackrel{?}{=} 0$$

$$\Rightarrow (\ddot{y}_1 + 2\xi\omega_n\dot{y}_1 + \omega_n^2 y_1) + (\ddot{y}_2 + 2\xi\omega_n\dot{y}_2 + \omega_n^2 y_2) \stackrel{?}{=} 0 \checkmark$$

$$\therefore \boxed{y(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}} \quad \text{⑨}$$

$s_{1,2}$ defined in Eq ⑧ $\forall \xi > 1.0$
and $s_{1,2} < 0$

b) $y(t)$ must also satisfy ICs

$$\text{Eq. 9} \Rightarrow \left. \begin{array}{l} y(0) = A_1 + A_2 = y_0 \\ \dot{y}(0) = A_1 s_1 + A_2 s_2 = \dot{y}_0 \end{array} \right\} \Rightarrow \begin{array}{l} \text{determine} \\ A_1 \text{ and } A_2 \end{array}$$

~~Solving~~ $\Rightarrow$

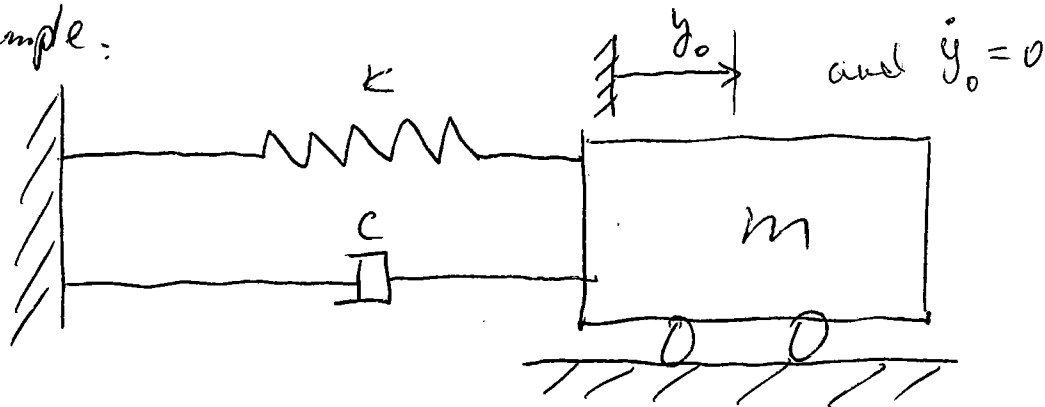
Yes, Eq. 9 is the right expression for $\zeta_1 > 1.0$

Solving A_1 and $A_2 \Rightarrow$

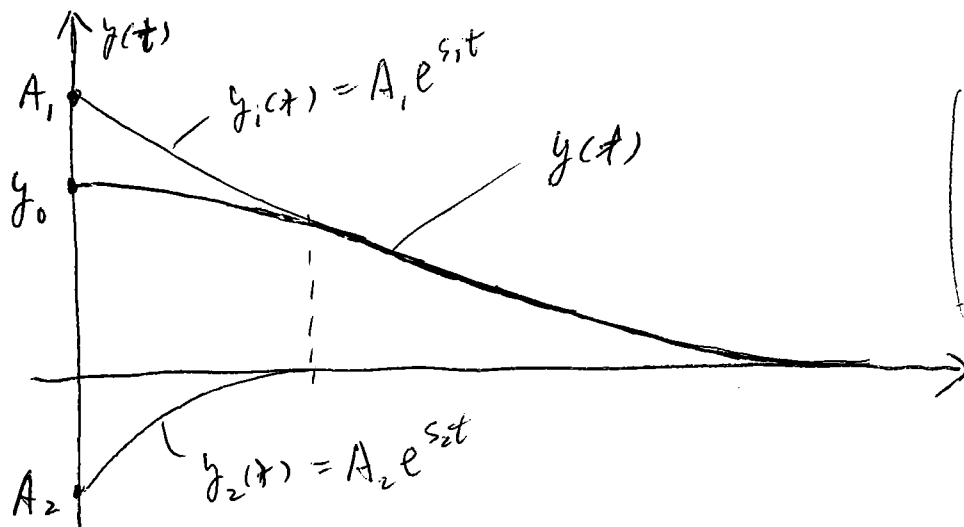
$$A_1 = \frac{y_0 \omega_n \left(\frac{c}{2} + \sqrt{\frac{c^2}{4} - 1} \right) + \dot{y}_0}{2 \omega_n \sqrt{\frac{c^2}{4} - 1}} \quad (10)$$

$$A_2 = \frac{-y_0 \omega_n \left(\frac{c}{2} - \sqrt{\frac{c^2}{4} - 1} \right) - \dot{y}_0}{2 \omega_n \sqrt{\frac{c^2}{4} - 1}} \quad (11)$$

Example:



$y(t) = ?$



$$\frac{c}{2} = \frac{1}{2} \frac{c}{\sqrt{\frac{K}{m}}} > 1.0$$

$$s_1 = \left(-\frac{c}{2} + \sqrt{\frac{c^2}{4} - 1} \right) \omega_n$$

$$s_2 = \left(-\frac{c}{2} - \sqrt{\frac{c^2}{4} - 1} \right) \omega_n$$

No vibration under its own.

$\frac{c}{2} > 1.0 \Rightarrow$ overdamped system

case ② $\left[\zeta = 1.0 \right] \xRightarrow{\text{Eq. ⑧}} s_1 = s_2 = -\omega_n$

Then Eq. ⑥ $\Rightarrow y_1(t) = A_1 e^{-\omega_n t}$ — (can't satisfy ICs alone)

and $y_2(t) = A_2 t e^{-\omega_n t}$ — (can be verified to satisfy Eq. ⑥)

So, $y(t) = A_1 e^{-\omega_n t} + A_2 t e^{-\omega_n t}$

b) Honor ICs $\Rightarrow$

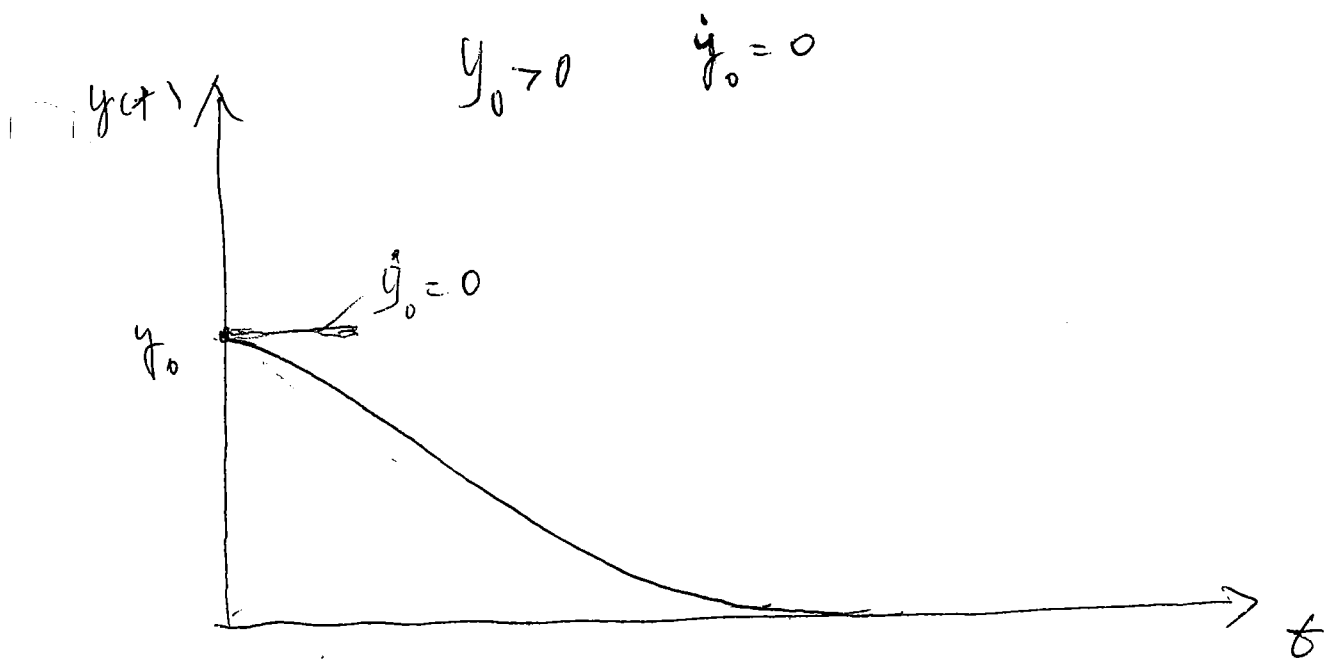
$$y(0) = A_1 = y_0$$

$$\dot{y}(0) = -A_1 \omega_n + A_2 = \dot{y}_0$$

$$\Rightarrow \begin{cases} A_1 = y_0 \\ A_2 = \dot{y}_0 + y_0 \omega_n \end{cases} \quad (12)$$

$$\therefore y(t) = \left[y_0 + (\dot{y}_0 + \omega_n y_0) t \right] e^{-\omega_n t} \quad (13)$$

Response to the example,



No vibration under its own.

$\zeta = 1.0 \Rightarrow$ critically damped system

Case ③ $0 < \zeta < 1.0$ Eq. ⑧ $\Rightarrow s_{1,2}$ are complex conjugates

$$s_{1,2} = -\omega_n \zeta \pm i \omega_n \sqrt{1 - \zeta^2}, \quad i = \sqrt{-1}$$

Eq. ⑥ $\Rightarrow y(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$

$$= A_1 e^{(-\omega_n \zeta + i \omega_n \sqrt{1 - \zeta^2})t} + A_2 e^{(-\omega_n \zeta - i \omega_n \sqrt{1 - \zeta^2})t}$$

$$= e^{-\omega_n \zeta t} (A_1 e^{i \omega_d t} + A_2 e^{-i \omega_d t})$$

$$= e^{-\zeta \omega_n t} \left[\underbrace{(A_1 + A_2)}_{B_1} \cos \omega_d t + i \underbrace{(A_1 - A_2)}_{B_2} \sin \omega_d t \right]$$

$$\begin{aligned} e^{i \omega_d t} &= \cos \omega_d t + i \sin \omega_d t \\ e^{-i \omega_d t} &= \cos(-\omega_d t) + i \sin(-\omega_d t) \\ &= \cos \omega_d t - i \sin \omega_d t \end{aligned}$$

$$\therefore y(t) = e^{-\omega_n \zeta t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t) \quad (14)$$

$$\omega_d = \omega_n \sqrt{1 - \zeta^2} = \text{damped natural frequency}$$

(15)

b) $y(t)$ must honor ICs

Eq. ⑭ $\Rightarrow$

$$\begin{aligned} y(0) &= B_1 = y_0 \\ \dot{y}(0) &= -\omega_n \zeta B_1 + B_2 \omega_d = \dot{y}_0 \end{aligned} \Rightarrow B_1, B_2$$

⇒

$$\begin{aligned} B_1 &= y_0 \\ B_2 &= \frac{\dot{y}_0 + \omega_n \frac{8}{3} y_0}{\omega_d} \end{aligned}$$

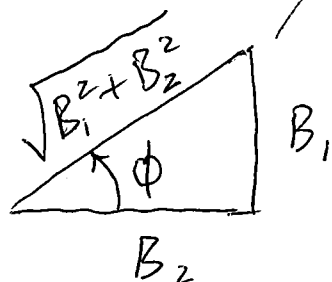
(16)

An alternative expression for $y(t)$

Eq. (14) ⇒

$$y(t) = \sqrt{B_1^2 + B_2^2} e^{-\omega_n \frac{8}{3} t} \left[\underbrace{\frac{B_1}{\sqrt{B_1^2 + B_2^2}}}_{\sin \phi} \cos \omega_d t + \underbrace{\frac{B_2}{\sqrt{B_1^2 + B_2^2}}}_{\cos \phi} \sin \omega_d t \right]$$

define a reference triangle:



Let $A = \sqrt{B_1^2 + B_2^2}$

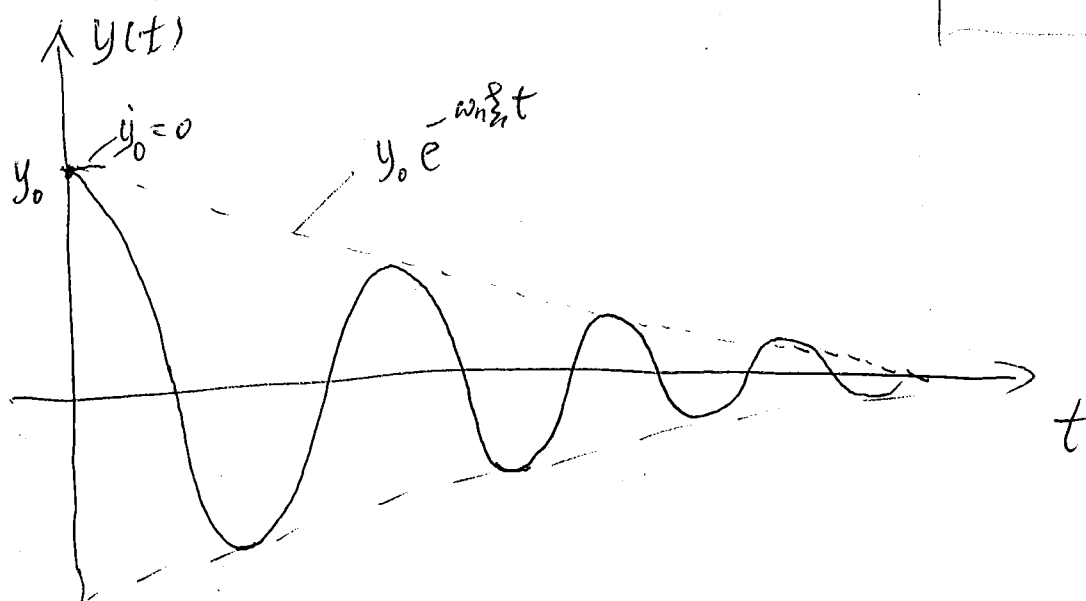
$$\therefore y(t) = A e^{-\omega_n \frac{8}{3} t} \sin(\omega_d t + \phi) \quad (14')$$

$$\begin{aligned} A &= \sqrt{B_1^2 + B_2^2} \\ \phi &= \tan^{-1} \frac{B_1}{B_2} \end{aligned}$$

(16.1)

The example again: $y_0 > 0, \dot{y}_0 = 0 \Rightarrow \phi = \tan^{-1} \frac{\sqrt{1-\xi^2}}{\xi}$
 $y(0) = A \sin \phi \Rightarrow A = \frac{y_0}{\sin \phi}$

no need



$0 < \xi < 1.0$ develops free vibration
 $\Rightarrow$ underdamped system

If $\xi = 0, \omega_d = \omega_n$, Eq. (14) $\Rightarrow$

$$y(t) = A \sin(\omega_n t + \phi)$$

$\Rightarrow$ undamped system.