

Today, we will:

- Discuss Fjortoft's theorem – a further necessary condition for inviscid instability
- Discuss an example problem – instability in a 2-D wake (JMC PhD thesis)

Last time → must be an inflection pt. to have the potential for instability.

→ This is a necessary but not sufficient condition for instability

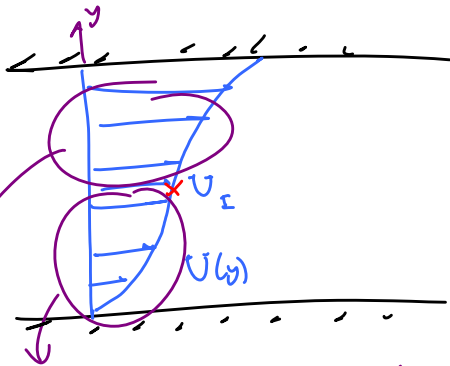
Fjortoft's theorem → A necessary condition for instability is that

$$U_{yy} (U - U_I) < 0 \text{ somewhere in the basic flow}$$

★ Necessary but not sufficient

(U @ inflection pt.)

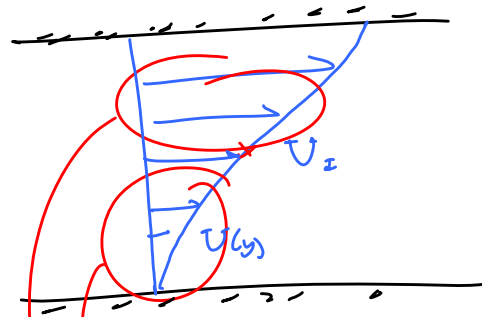
e.g. Couette flow profiles – both have inflection pts A B



lower half, $U_{yy} < 0$ (slope decreasing with y)
 $\therefore U - U_I < 0$
 $U_{yy} (U - U_I) > 0$

upper half, $U_{yy} > 0$ (slope increasing with y)
 $\therefore U - U_I > 0$
 $U_{yy} (U - U_I) > 0$

$U_{yy} (U - U_I) > 0$ everywhere
 \therefore **STABLE**



lower half $U_{yy} > 0$
 $U - U_I < 0$
 $U_{yy} (U - U_I) < 0$

upper half $U_{yy} < 0$
 $U - U_I > 0$
 $U_{yy} (U - U_I) < 0$

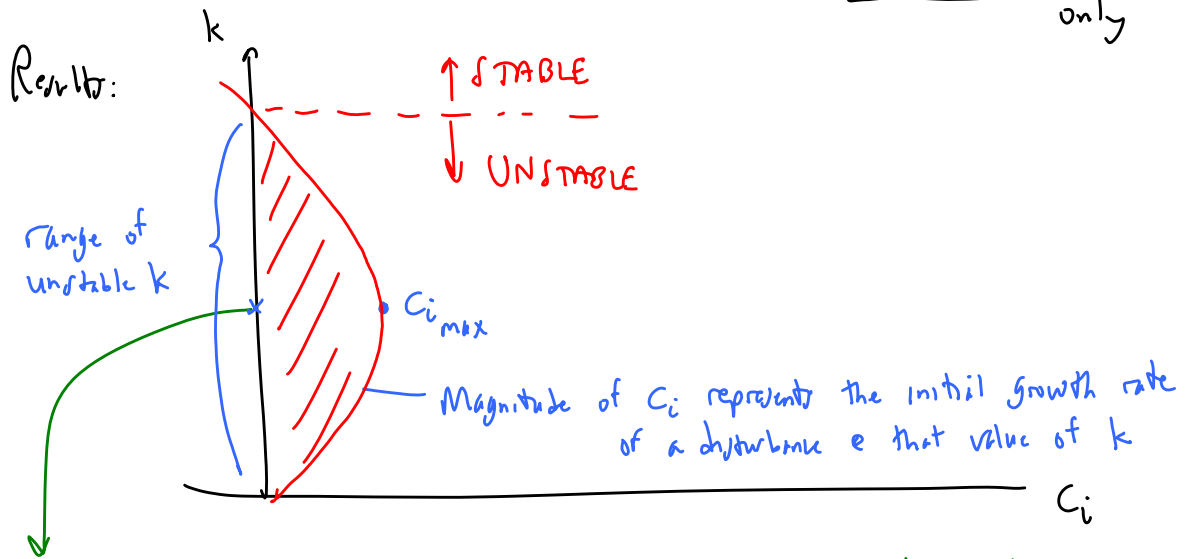
$U_{yy} (U - U_I) < 0$ everywhere

Potentially unstable

C. Typical Solutions of Rayleigh's eq.

- Consider a basic state that satisfies both Rayleigh & Fjortoft's criteria.
- Solve Rayleigh eq. & find eigenvalues

We are considering the TEMPORAL MODE only



This k corresponding to $C_{i_{max}}$ is the one we would expect to see (most likely to be observed)

Typically, very high wavenumbers are stable

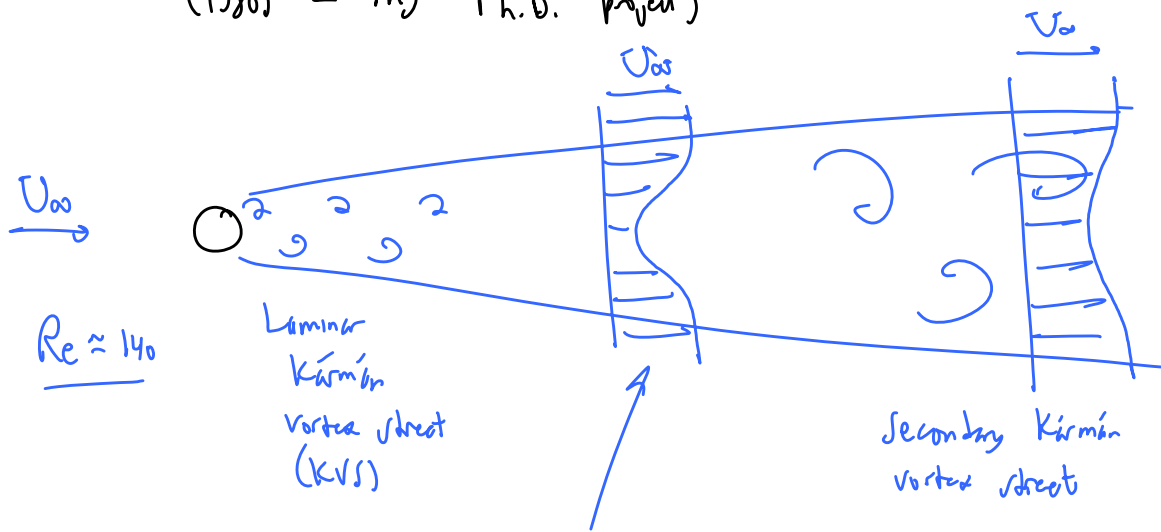
recall $k = \frac{2\pi}{\lambda} \Rightarrow$ high $k =$ wavenumber means short wavelength (or high frequency)

Typically, very short wavenumbers are unstable, but as $k \rightarrow 0$, it becomes stable again.

[long wavelength disturbances (low freq. disturbances) are unstable]
very short " " (high " ") are stable \star

d. Example - far wake of a circular cylinder

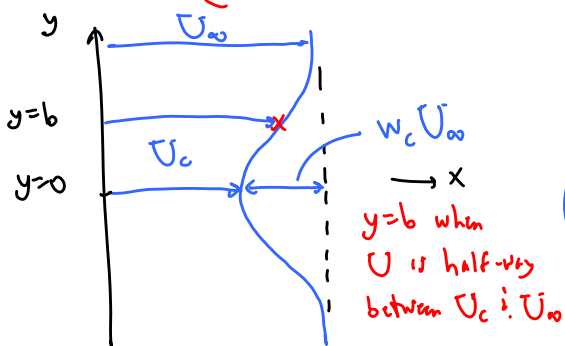
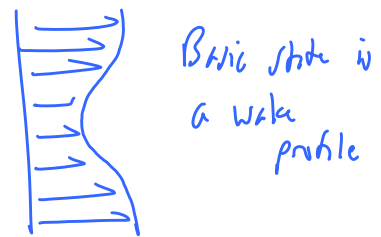
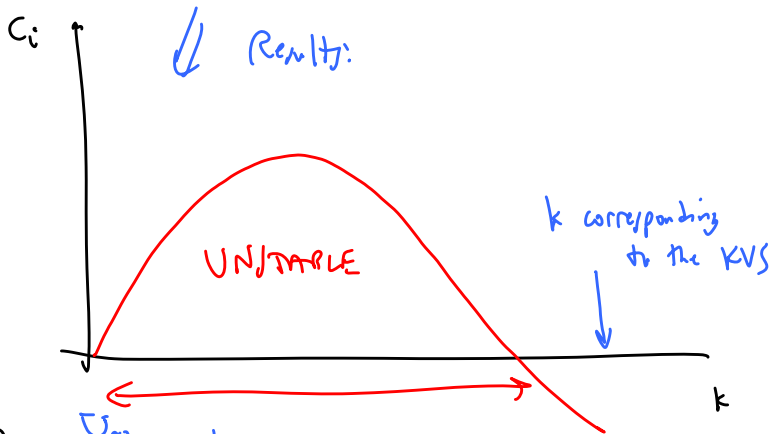
(1980's - my Ph.D. project)



by ≈ 100 diameters
downstream, the
original KVS
disappeared!

Rayleigh Eq \rightarrow inviscid stability analysis

I allows 2-D, //, inviscid disturbances, linear, temporal mode



$w_c \equiv$ nondimensional velocity defect @ centerline
 $U_c =$ centerline velocity

$$w_c = 1 - \frac{U_c}{U_{\infty}}$$

Define W = normalized wake defect

$$W\left(\frac{y}{b}\right) = \frac{U - U_\infty}{U_c - U_\infty} = e^{-a\left(\frac{y}{b}\right)^2}$$

where $a = \ln 2 \rightarrow$ so that $W\left(\frac{y}{b} = 1\right) = 0.5$
 $W(0) = 1$

Gaussian shape is a good curve fit for the wake profile @ any value of x (downstream)

$$U = U_\infty + W(U_c - U_\infty)$$

$$= U_\infty \left[1 + W \left(\frac{U_c}{U_\infty} - 1 \right) \right] = U_\infty (1 - w_c W) \rightarrow$$

$$\frac{U}{U_\infty} = 1 - w_c W$$

Also, like Kundu, let $y = \frac{y}{b}$, $U = \frac{U}{U_\infty}$

$$\begin{aligned} \therefore U &= 1 - w_c W \\ U_y &= -w_c W_y \\ U_{yy} &= -w_c W_{yy} \end{aligned}$$

[y subscript means $\frac{d}{dy}$]

Play into Rayleigh eq.

$$\text{Rayleigh eq. } (U - c) (\phi_{yy} - k^2 \phi) - U_{yy} \phi = 0 \quad (1)$$

$$\left[\frac{1}{w_c} (1 - c) - W \right] (\phi_{yy} - k^2 \phi) + W_{yy} \phi = 0$$

$$\text{let } c_u = \frac{1}{w_c} (1 - c) = \text{universal wake wave speed}$$

Universal wake Rayleigh eq.
for temporal stability.

$$\star (W - c_u) (\phi_{yy} - k^2 \phi) - W_{yy} \phi = 0$$