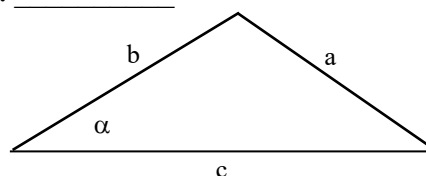


1) Print hardcopy of this sheet. Estimate angle α by eye. α 30°

2) Write an equation to determine angle α as a function of lengths a , b and c .

Law of Cosines $a^2 = b^2 + c^2 - 2bc \cos \alpha$



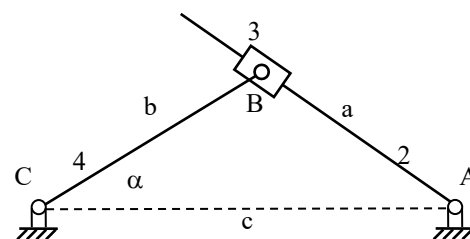
3) Measure a , b and c using mm. a 32 mm b 35.5 mm c 56.5 mm

4) Compute α using parts 2) and 3) above. α 31.3°

5) Measure α with a protractor. α 30.5°

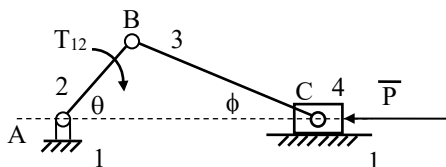
6) Links AC and BC are rigid. Determine $\dot{\alpha}$ when \dot{a} is +10 mm/s at this position. Use link lengths from 3) above.

first time derivative of Equation 2 $\dot{\alpha}$ 0.3143 rad/s
 $2a\dot{a} = 2bc\dot{\alpha}\sin\alpha$ 18.01 deg/s
 $\dot{\alpha} = \dot{a} a / (bc \sin \alpha)$

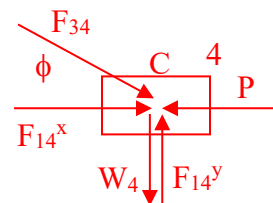


7) What is this mechanism? inverted slider crank

8) Draw a **complete** free-body diagram of slider block 4 for static equilibrium including friction.



assume impending motion to the left



9) What is this mechanism? in-line slider crank

10) Complete the matrix multiplication.

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{Bmatrix} 5 \\ 6 \end{Bmatrix} = \begin{Bmatrix} 17 \\ 39 \end{Bmatrix}$$

11) Invert the matrix.

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}^{-1} = \begin{bmatrix} -2 & 1 \\ 1.5 & -0.5 \end{bmatrix}$$

$$\text{inv} = [\text{cofac}]^T / \det$$

$$\det = -2$$

$$\text{cofac} = \begin{bmatrix} 4 & -3 \\ -2 & 1 \end{bmatrix}$$